

## ADVANCES IN METROLOGY

Light is considered as an electro magnetic wave of sinusoidal form. The high point of wave is called the crest and the low point is called trough. The distance between two crests or two troughs is called the wavelength. The time taken by light in covering one wavelength is called time period.

The amplitude of a wave is the distance from the still position to the top of a crest or to the bottom of a trough. The frequency of a wave is the number of waves passing a point in a certain time (i.e) the velocity of transmission.

Light is produced by any two methods

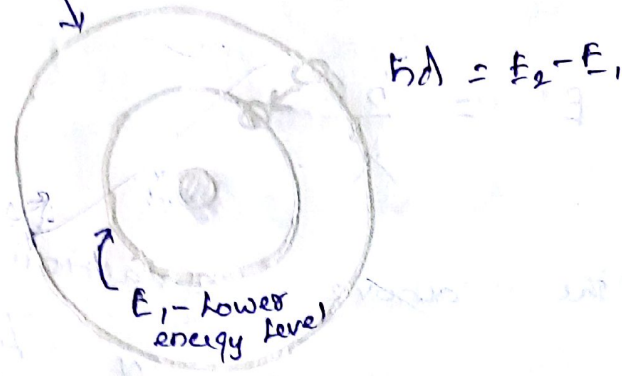
- \* Incandescence is the emission of light from hot matter ( $T_{emp} \geq 3000K$ )
- \* Luminescence is the emission of light when excited electrons fall to lower energy level.

Monochromatic Light is a narrow band of spectrum of visible light having the same wave length or colour.

## LASER

In coherent beam, all the waves have the same frequency and phase. Lasers have greater coherent length of a light beam refers to the distance over which the beam stays in phase with itself.

\* An electromagnetic radiation is emitted whenever a charged particle such as an electron drops from a higher energy state,  $E_2$  to a lower energy state  $E_1$ .



The difference in energy level across which an excited electron drops determines the wavelength of emitted light. The wavelength or frequency of light determines its colour.

According to Quantum Mechanics, light is made up of particles called photons. Which exhibit both particle like and wave like properties.

$$E = h\nu$$

$\nu$  is the frequency of light and  $h$ ,

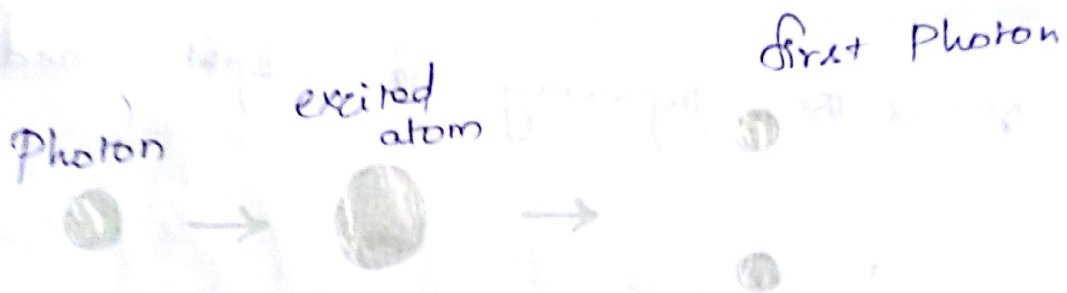
$$\lambda \nu = c$$

$\lambda$  is the wavelength of light and  $c$  is the speed of light in vacuum.

$$E = \frac{hc}{\lambda}$$

From the above equation we see that longer the wavelength of light lower the energy of photon. So the ultraviolet light is more energetic than infrared light.

When an electron is in an excited energy state, it must eventually decay to a lower level giving off a photon or radiation. This event is called spontaneous emission.



A photon strikes an excited atom

New photon

The atom emits a

New photon

Just like the first one.

There is a probability that the passing photon will cause the electron to decay in such a manner that a photon is emitted at exactly the same wavelength, in exactly the same direction and with exactly the same phase as the passing photon. This process is called a 'stimulated emission'.

The normal thermal population in any material will have most of the electrons in the steady state ground level. But it is preferred to have most of the electrons in the excited state so that we can get more photons through stimulated emission. Thus a population inversion.

The condition of having enough excited or higher energy states distributed in a material, that a chain-reaction of stimulated emission can occur is called population inversion.

Comparison between Laser Light and  
Light from an incandescent lamp.

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### LASER LIGHT

Has single wavelength  
(i.e) Spectrally pure or  
Monochromatic.

Coherent radiation i.e  
all photons are in  
Phase

High directionality  
Prevails over long  
distance

### Types of Laser.

There are various kinds of  
Lasers like solid state, ~~gas~~ Gas,  
Liquid and semiconductor Lasers. The  
different Lasers and their applications  
are given below.

### ORDINARY LIGHT

Has a mixture of  
Various wavelengths i.e  
Polychromatic.

Incoherent radiation.

No Directionality.

Does not prevail  
long.

# \* Types of Laser :

Solid state :

Ruby Laser

YAG Laser

Liquid Laser :

Dye Laser

He-Ne Laser

Gas Laser :

Argon ion Laser

CO<sub>2</sub> gas Laser

Semi conductor Laser :-

Ga As Al Laser

In Ga Al P Laser

In Ga Al P Laser

These are the types of

Laser are available.

# Advantages of Laser

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\* Lasers are more intensive than any other monochromatic source.

Micrology lasers are low power

Instruments.

Lasers have wide dynamic range, low optical cross talk and high contrast.

Lasers are highly precise, accurate and can prevail over long distance.

Lasers allow fabrication of fine structures with high quality avoiding mechanical stress.

Lasers facilitate rapid non-contact drying of soft, delicate or hot moving parts.



# Applications :-

## Manufacturing :-

for high Quality cutting, drilling, welding and surface treatment etc.,.

## Metrology :-

for Contact Measurement of parts, for long distance range finding and Navigation, for scanning bar codes etc.,.

## Medical :-

for surgery, kidney stone, treatment, eye treatment, in dentistry, for diagnosis, like laser microscopy.

## Data Storage :-

for optical data storage eg (compact disk, CD, DVD, etc) for holography.

## Communication :-

for optical fibre communication, for free space communication, (eg Inter satellite communications).

# SCANNING LASER GYROSCOPE

A scanning laser gyroscope  
or non-contact dimensional  
Measurements.

The main components in a scanning  
laser gyroscope are

Transmitting Unit

Photo Cell (Receiver)

Microprocessor or Control Unit.

Signal from the diode entering the  
photo cell is processed by a microprocessor  
to provide display of the dimension.

The scanning laser gyroscope is used  
to measure the roundness and diameter  
of hot steel bars. It provides an  
accuracy of 0.025 mm for 5-25 mm  
diameter objects and offers a

## Laser Telemetric System :-

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Laser telemetric system is used for high speed, non contact dimensional and positional measurement and control. The system measures outside diameters, multiple dimensions or part positions of either opaque or transparent objects.

The laser telemetric system consists of three components: Transmitter, receiver and Processor electronics.

## Photo Diode Array Imaging :-

This system consists of a laser source, imaging optical, photodiode array, signal processor and display unit. Here, the shadow of a stationary part is projected on a solid state diode array image sensor.

## INTERFERENCE :-

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The phenomenon in which two waves of greater or lower amplitude is called Interference.

## Principle of Superposition :-

When two or more waves of the same type are incident at the same point, then the total displacement at that point is equal to the vector sum of the displacement of the individual waves.

On the other hand, if they are out of phase, the resultant wave amplitude is the difference of the individual amplitudes which results in decreased brightness.

If the amplitude of both the waves are same, then they nullify each other and other will result in darkness.

The conditions necessary for the interference of light waves at a place are

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The source should continuously emit waves of the same wavelength or frequency

The amplitudes of the two interfering waves should be equal or nearly so for obtaining interference fringes.

The surfaces must be reflective

The source should be narrow.

## INTERFEROMETRY :-

Metre was defined as the distance between two finely scribed lines on the Platinum Iridium bar.

In order to reduce the dependence on the physical standard, the process which was prone to errors, the wave length of pure monochromatic light is used as the natural standard of length.

## Interferometer :-

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It is an instrument that generates and compares the difference between two light waves which are reflected off two different surfaces. It utilizes the effect of interference.

## Applications of Interferometers :-

Measurements of length & area  
Small changes in length.

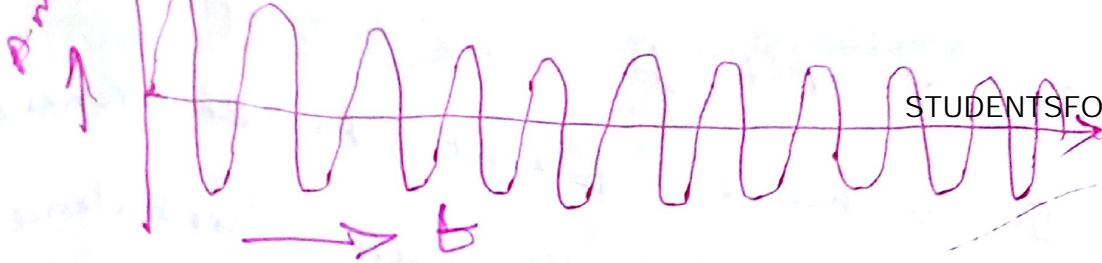
Optical testing.

Studies of surface structure.

Wavelength measurements.

## AC Laser Interferometry :-

A D.C Interferometer System mixes out of phase light beams of the same frequency where as the A.C system mixes beams of two slightly different frequencies, permitting the distance information to be carried on a.c wave form.



The envelope frequency is given by the difference of the two frequency components ( $f_1 - f_2$ ) of the source radiation.

So, an A.C Laser interferometer measures mirror displacement by measuring the phase change due to the Doppler effect. It gives a much improved signal to noise ratio over amplitude modulation.

### Description of A.C Laser Interferometer.

1. Two frequency laser source.
2. Optical elements.
  - (i) Beam splitter.
  - (ii) Beam Benders.
  - (iii) Retro reflectors.
3. Laser lead's measurement receiver.
4. Measurement display.

## Advantages of ACH :-

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It is more tolerant to environmental factors like dust, smoke, air turbulence, etc that attenuate laser beam intensity.

It has high repeatability and resolution of displacement measurement.

It has high accuracy of measurement.

It facilitates to maintain long range optical path (60 m).

It is easy to install.

Alignment is good.

## Laser Interferometry :-

Conventional light source emit waves of different frequencies and at different time from different point in the source. Hence they are not

suitable for obtaining interference fringes.

Laser devices produce intense beam of light which are monochromatic coherent and highly collimated.



# Type of Laser Interferometer

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Homodyne or Single - Frequency (or)  
DC Laser  
Heterodyne (or) Dual - Frequency or  
AC Laser Interferometer.

## Single Frequency DC Interferometer

For two beams of light to interface, the beams must have same polarization state. A Polarizer transmits only a single polarization state.

The orientation of the transmitted polarization state is based on the angle of the polarizer.

Change the polarization state of light. eg :- from horizontal to vertical.

A Polarization beam splitter separates the source into beams with opposite polarization states referred to as the reference and measurement legs.

The homodyne or single frequency DC Interferometer is an improved version of the Michelson Interferometer.

### Coordinate Measuring Machine :-

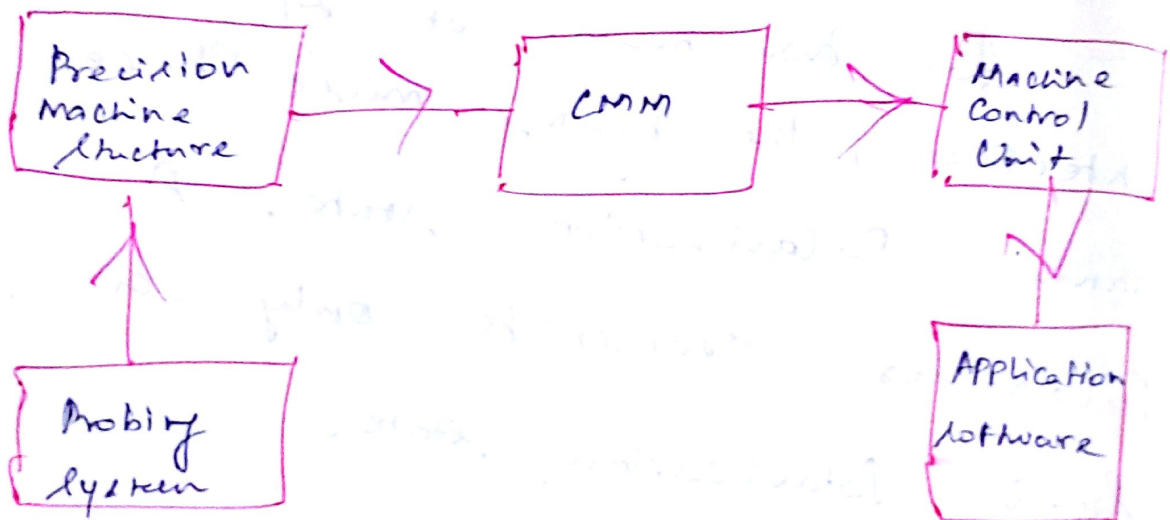


Diagram of Coordinate measuring system.

A Coordinate measuring system machine consists mainly of four elements. They are,

- \* The Main structure including  
the area of motion,
- \* The Drivably system,
- \* The Machine controller and Computer  
hardware.

\* Suitable Application software

### Types of CMM :-

Cmm are classified as follows :-

1. According to Control system

(i) Manual CMM or Free Floating  
CMM

(ii) Computer Numerical Control (CNC)

(or) Direct Computer Control (DCC)

2. According to design of Main  
structure or Orientation of Probe arm

(i) Bridge type.

(ii) Cantilever type.

(iii) Column type.

(iv) Gantry type.

(v) Horizontal type.

Accuracy to Mounting Systems

(i) Bench top.

(ii) Free standing.

(iii) Portable and Hand Held.

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Advantage of CMM :-

\* Reduced inspection cycle time.

\* Flexibility.

\* Reduce operator error

\* Improved accuracy and Precision.

\* Improved Productivity.

PROBES :-

CMM Measure work place dimensions by moving a sensing device, called a Probe.

The Probe Contact Physical measurements into electrical signals by using various measuring systems within the Probe structure.

Common Probes Fall into two general categories.

\* Tactile (or) Contact Probe.

\* Non-Contact Probe.

Contact Probe :

Its name suggests, gather data by physically touching the workpiece in the acquisition of the measuring point takes place by probing with stylus. Contact probes are classified.

\* Hard (or) fixed Probe.

\* Touch Trigger Probe.

\* Measuring type (or) displacement Probe.

Non-Contact Probes :-

Non-Contact Probe also called Proximity Probe are used when part, accurate measurements are required with no physical contact with the part.

These probes enable the measurement of flexible parts that soft material and geometry might be distorted with a contact probe.

Applications of CMM :-

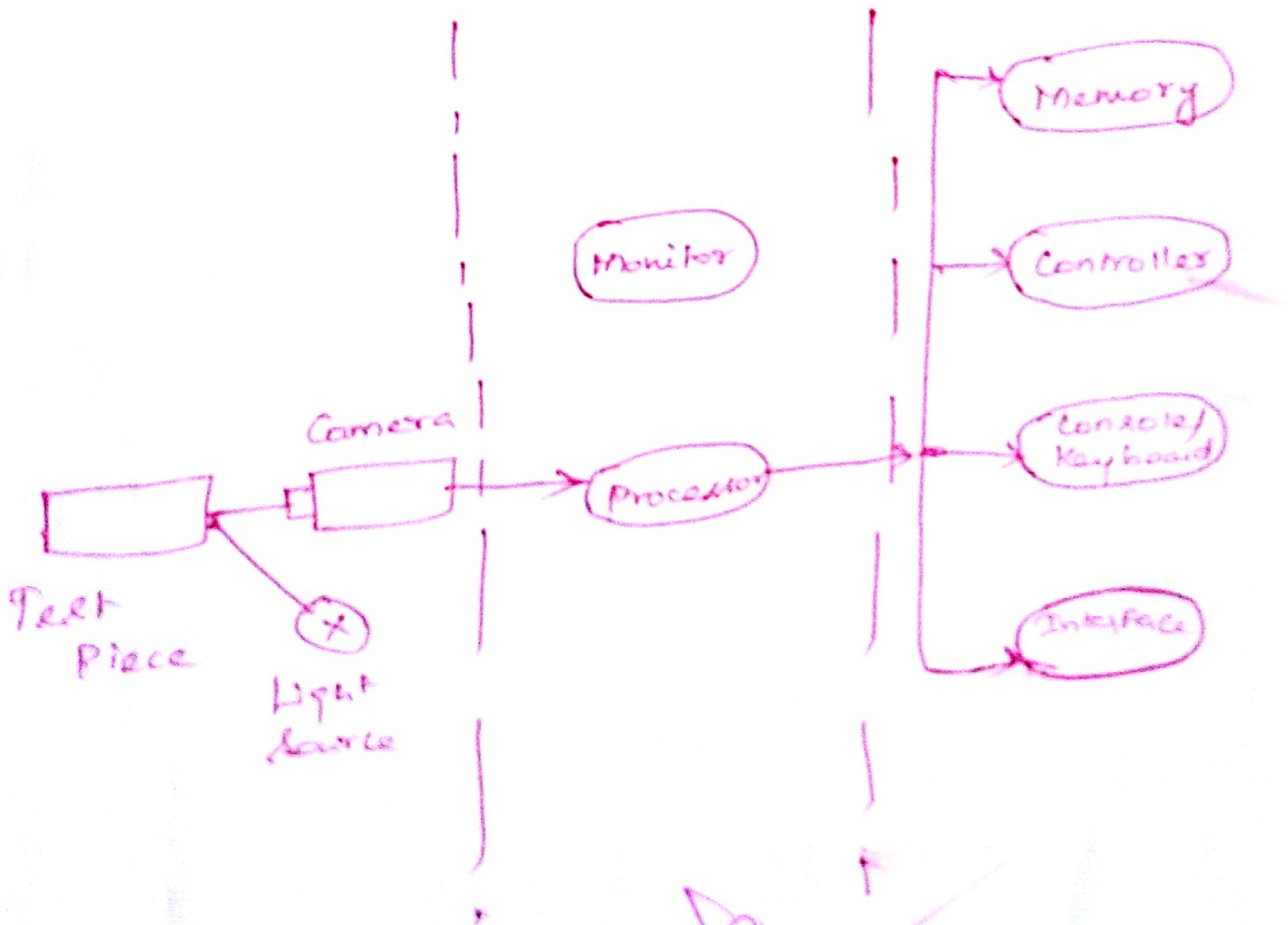
To check dimensional accuracy of part in various steps of production and of parts supplied by vendor.

To inspect test equipment, gauges and tools.

To determine shape and position, minimum metal condition, linkage of results, etc., which conventional machine can not perform.

# Machine Vision :-

Machine Vision is the ability of a computer to 'see'. Machine Vision is also called as 'Artificial Vision'. (or) Computer Vision. It is defined as a technique which allow a sensor to view a scene and drive a numerical or logical decision without further human intervention.



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